

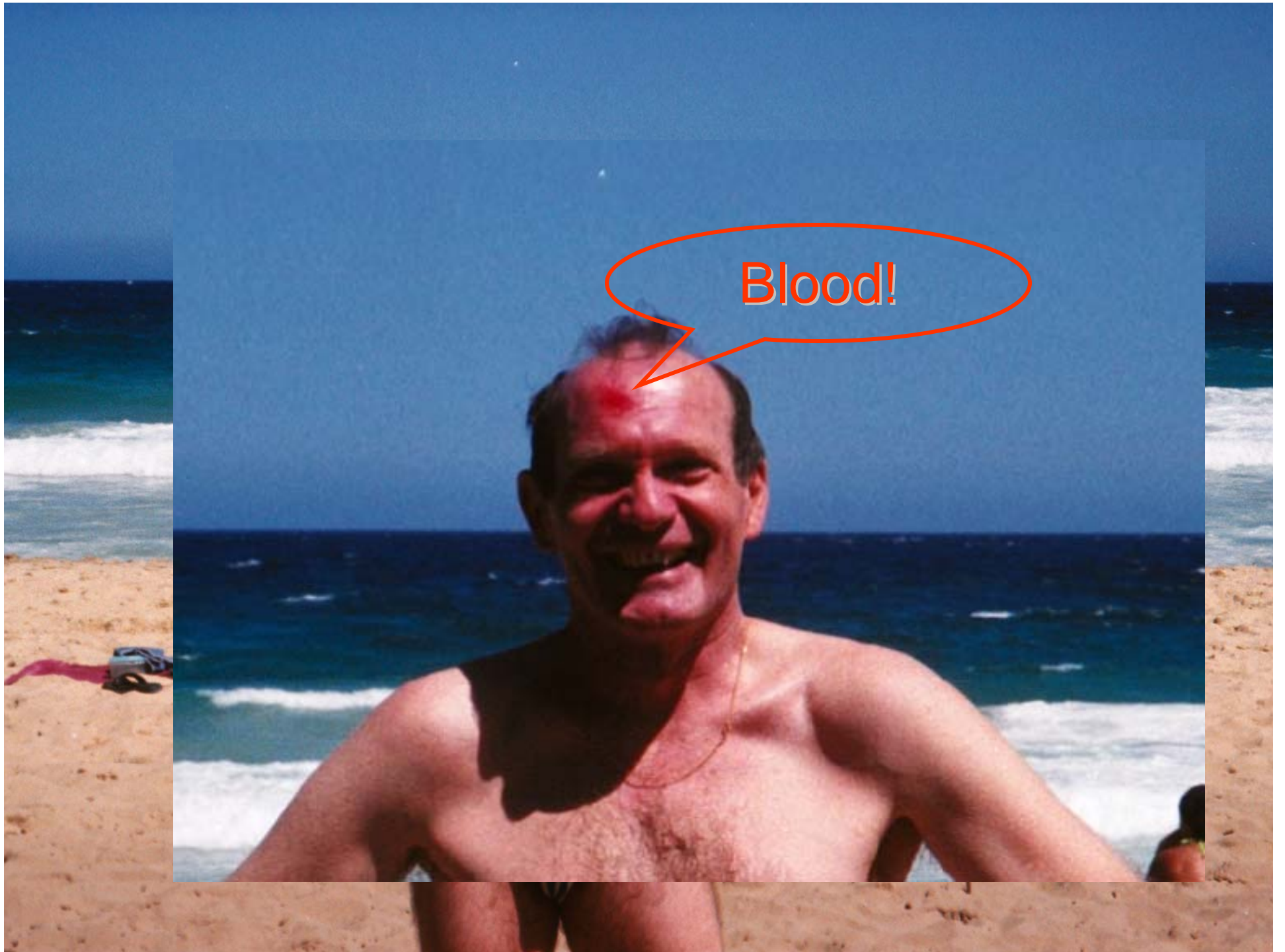
Maximum Likelihood Estimation for α -Stable AR and Allpass Processes

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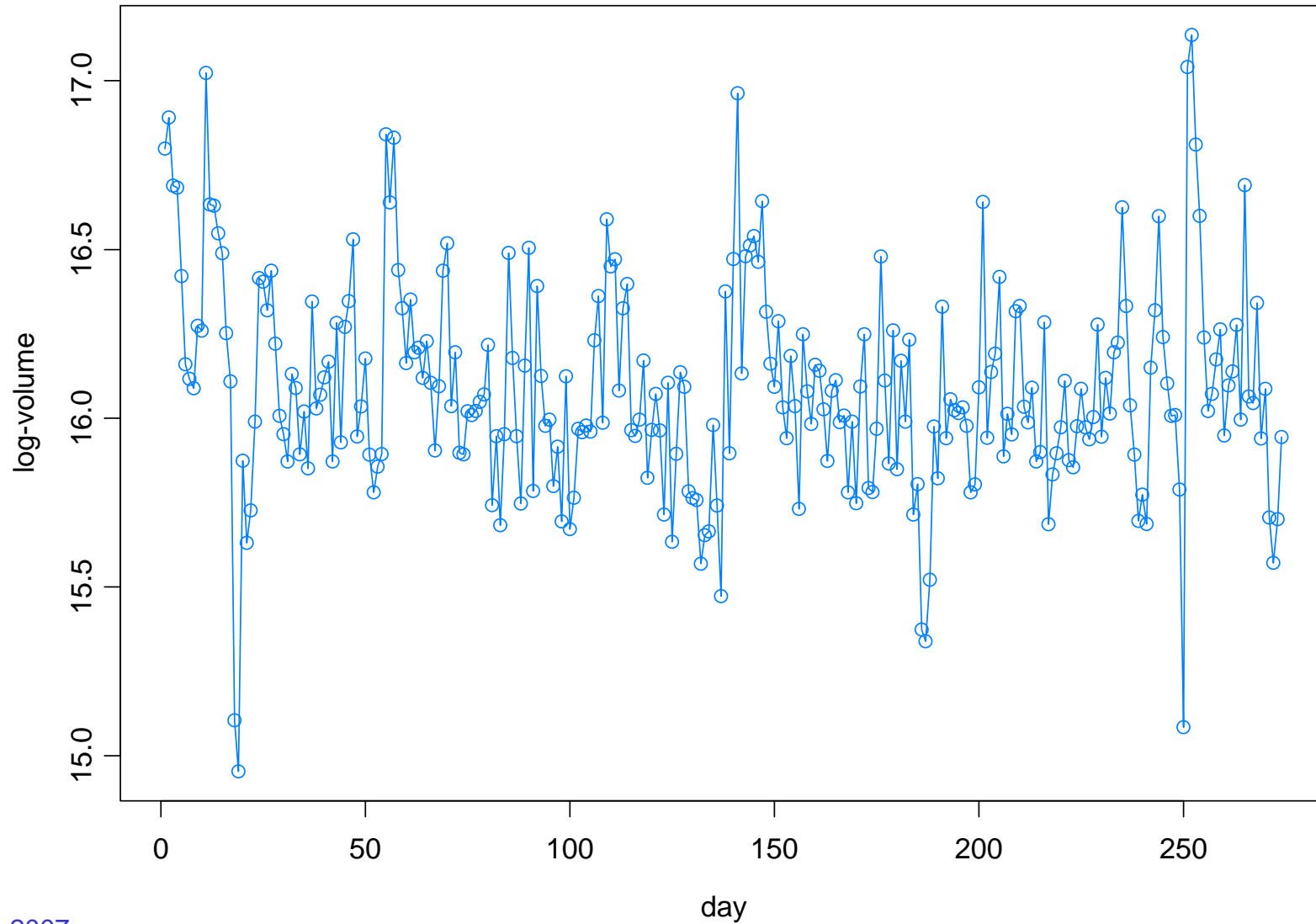
(<http://www.stat.columbia.edu/~rdavis>)



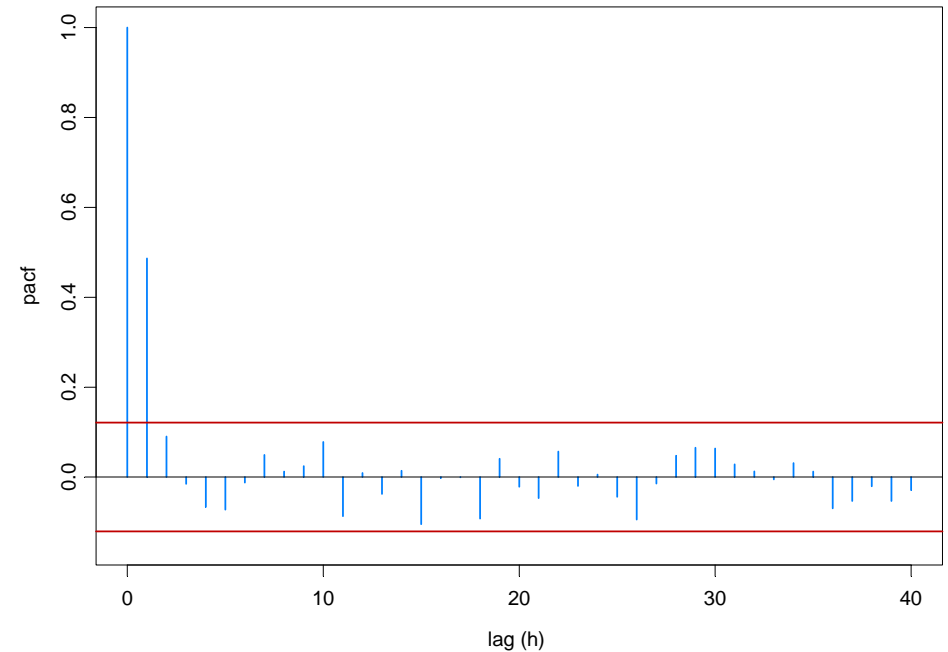
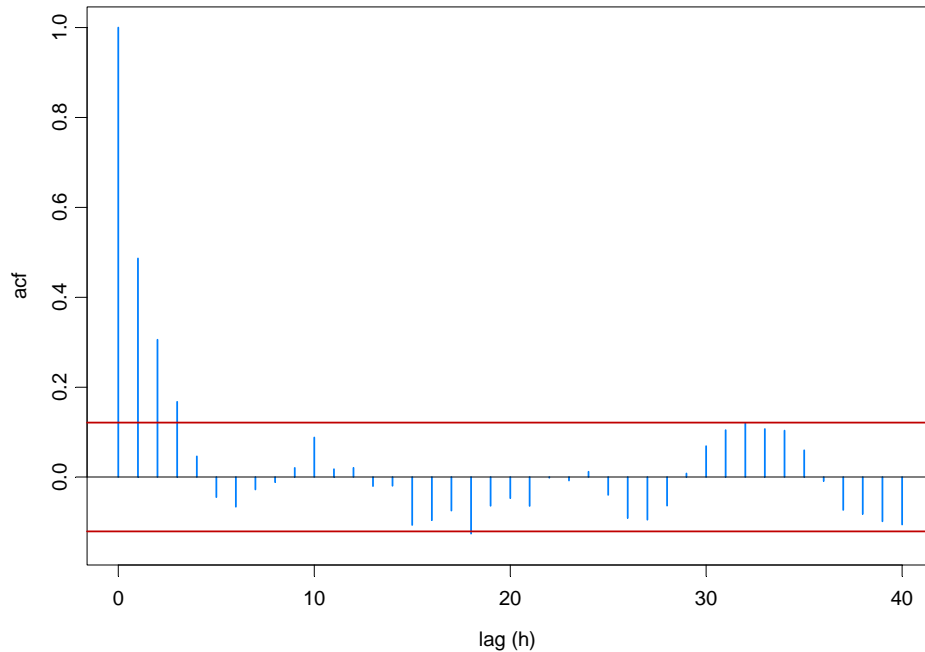
Blood!

1. Motivating Example

Log(volume) of Walmart stock 12/1/03-12/31/04



1. Motivating Example (cont)



Analysis suggests that $\{X_t\}$ follows an AR (1) or AR(2).

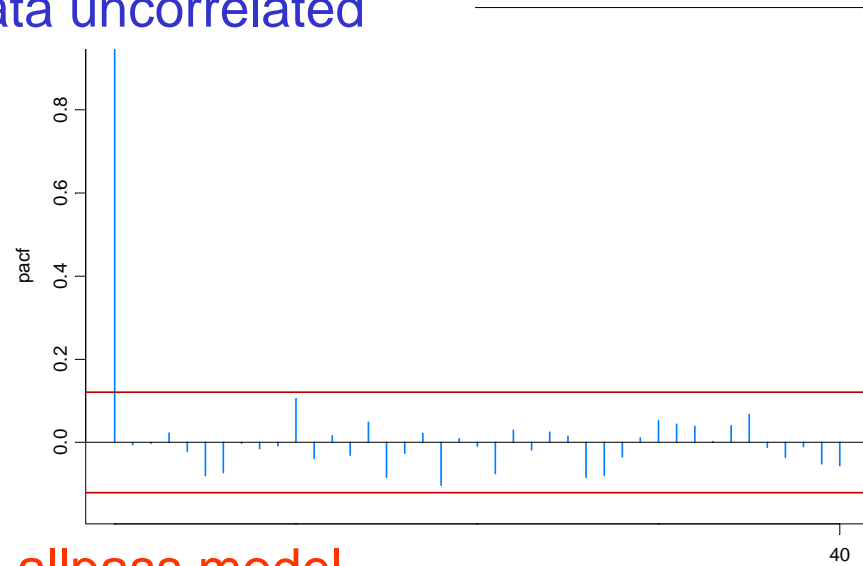
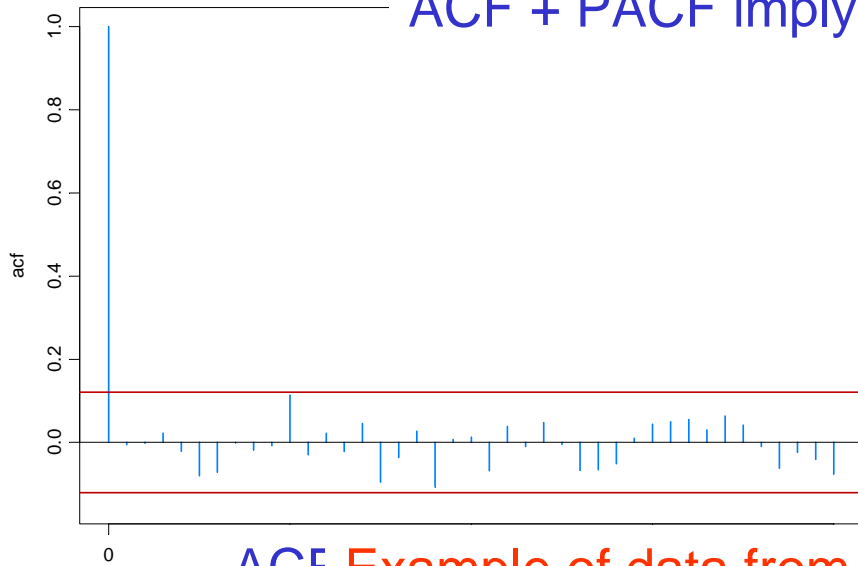
A *causal* AR(2) fit is

$$X_t = .4455 X_{t-1} + .1025 X_{t-2} + Z_t$$

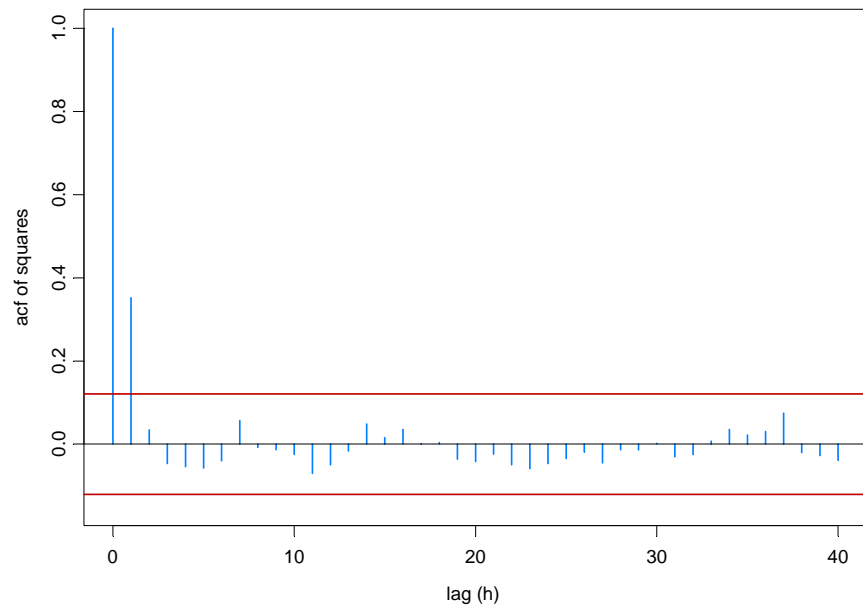
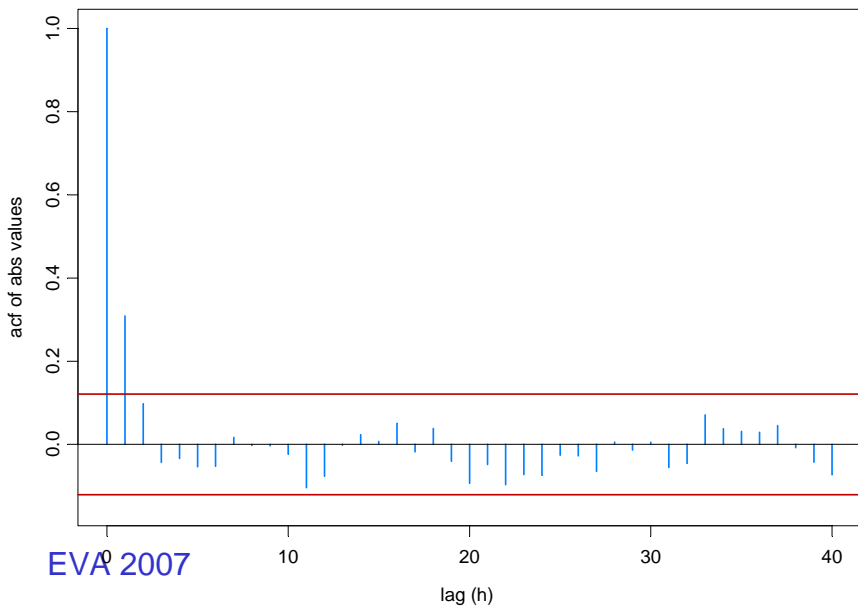
Are the estimated residuals iid?

Analysis of residuals from causal AR(2) fit

ACF + PACF imply data uncorrelated



ACF Example of data from an allpass model



Game Plan

1. Motivating example: Wal-Mart volume
2. Setup
 - AR models
 - Allpass models
 - Stable noise
3. Maximum likelihood estimation
4. Simulation results
5. Wal-Mart revisited

2. Setup—AR models

Assume $\{X_t\}$ follows an autoregressive model or an allpass model.

AR(p) model:

$$X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t, \text{ where } \{Z_t\} \sim \text{IID}$$

AR polynomial: $\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p$, $\phi(z) \neq 0$ for $|z| = 1$.

- **causal** if $\phi(z) \neq 0$ for $|z| \leq 1$, i.e., fcn of past values of Z_t

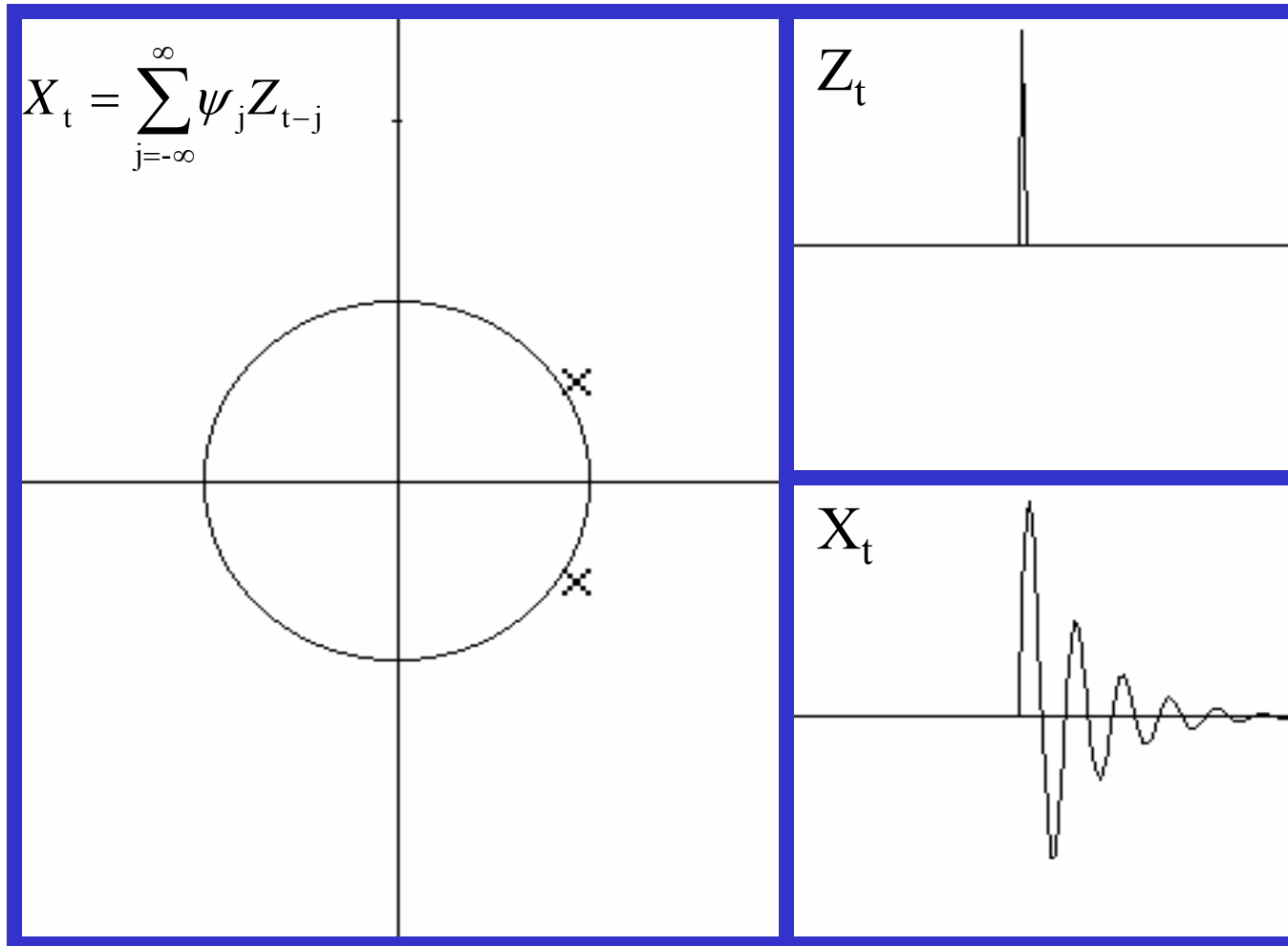
$$X_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$$

- **purely noncausal** if $\phi(z) \neq 0$ for $|z| > 1$, i.e., fcn of future values of Z_t

$$X_t = \sum_{j=p+1}^{\infty} \psi_j Z_{t+j}$$

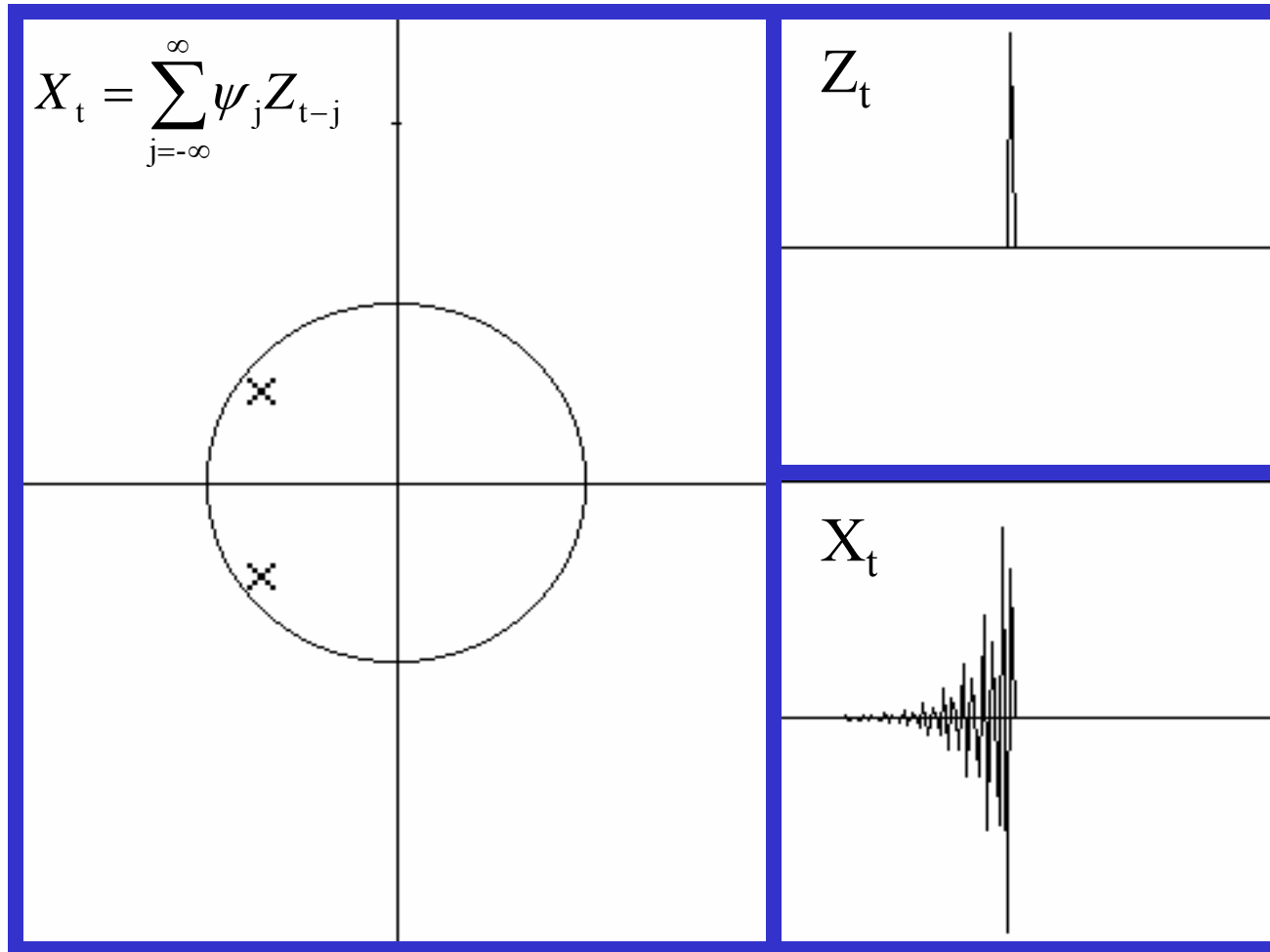
2. Setup—AR Models

Impulse response: causal & low frequency



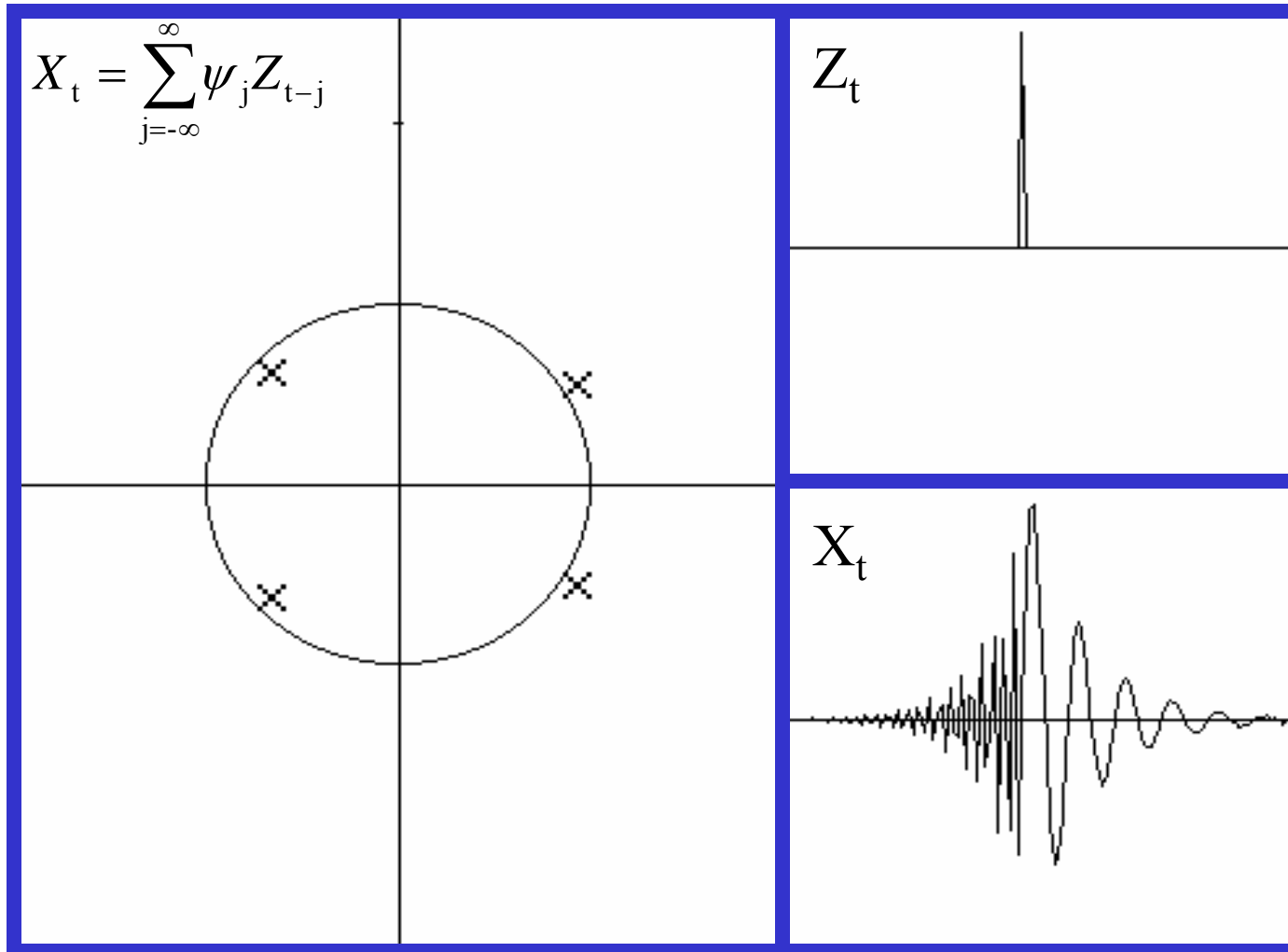
2. Setup—AR Models

Impulse response: noncausal & high frequency



2. Setup—AR Models

Impulse response: mixed causal (low frequency) & noncausal (high frequency)



2. Setup—Allpass models

Causal AR polynomial: $\phi(z) = 1 - \phi_1 z - \dots - \phi_p z^p$, $\phi(z) \neq 0$ for $|z| \leq 1$.

Define MA polynomial:

$$\theta(z) = -z^p \phi(z^{-1}) / \phi_p = -(z^p - \phi_1 z^{p-1} - \dots - \phi_p) / \phi_p$$

$\neq 0$ for $|z| \geq 1$ (MA polynomial is non-invertible).

Model for data $\{X_t\}$: $\phi(B)X_t = \theta(B)Z_t$, $\{Z_t\} \sim \text{IID (non-Gaussian)}$

$$B^k X_t = X_{t-k}$$

Examples:

All-pass(1): $X_t - \phi X_{t-1} = Z_t - \phi^{-1} Z_{t-1}$, $|\phi| < 1$.

All-pass(2): $X_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} = Z_t + \phi_1 / \phi_2 Z_{t-1} + 1 / \phi_2 Z_{t-2}$

2. Setup—Allpass models

Properties: *linear process with nonlinear behavior*

- causal, non-invertible ARMA with MA representation

$$X_t = \frac{B^p \phi(B^{-1})}{-\phi_p \phi(B)} Z_t = \sum_{j=0}^{\infty} \psi_j Z_{t-j}$$

- uncorrelated (flat spectrum)

$$f_X(\omega) = \frac{|e^{-ip\omega}|^2 |\phi(e^{i\omega})|^2}{\phi_p^2 |\phi(e^{-i\omega})|^2} \frac{\sigma^2}{2\pi} = \frac{\sigma^2}{\phi_p^2 2\pi}$$

- zero mean
- data are dependent if noise is non-Gaussian (e.g. Breidt & Davis 1991).
- squares and absolute values are correlated.
- X_t is heavy-tailed if noise is heavy-tailed.

2. Setup—Allpass models

Properties cont:

- Suppose the time series X_t follows a noncausal AR and/or a non-invertible MA process. For definiteness, suppose $\{X_t\}$ follows the noninvertible MA model

$$X_t = \theta_i(B) \theta_{ni}(B) Z_t, \quad \{Z_t\} \sim \text{IID.}$$

Step 1: Let $\{U_t\}$ be the residuals obtained by fitting a purely invertible MA model, i.e.,

$$\begin{aligned} X_t &= \hat{\theta}(B) U_t \\ &\approx \theta_i(B) \tilde{\theta}_{ni}(B) U_t, \quad (\tilde{\theta}_{ni} \text{ is the invertible version of } \theta_{ni}). \end{aligned}$$

So

$$U_t \approx \frac{\theta_{ni}(B)}{\tilde{\theta}_{ni}(B)} Z_t$$

Step 2: Fit a purely causal AP model to $\{U_t\}$

2. Setup—stable noise

The noise is assumed to have a nonGaussian stable distribution

Noise distribution: $\{Z_t\} \sim \text{IID}$ with a stable distribution

That is, Z_t has characteristic function given by

$$\varphi_0(s) = E\{\exp(isZ_t)\} = \exp\{-\sigma^\alpha |s|^\alpha [1 + i\beta \operatorname{sgn}(s) \tan(\pi\alpha/2)(|s|^{1-\alpha} - 1)] + i\mu s\}$$

where

- + **exponent** $\alpha \in (0,2)$
- + **symmetry parameter** $\beta \in (-1,1)$
- + **scale parameter** $\sigma > 0 \in (0,2)$
- + **location parameter** μ .

Density function: inverse Fourier transform

$$f(z; (\alpha, \beta, \sigma, \mu)) = (2\pi)^{-1} \int_{-\infty}^{\infty} e^{-isz} \varphi_0(s) ds$$

can be computed numerically reasonably quickly (Nolan, '97).

2. Setup—stable noise (cont)

Remarks:

1. There are a number of parameterizations of a stable distribution (see Zolotarev '86), but this is the one advocated by Nolan '01.

- differentiable wrt to \mathbf{z}
- differentiable wrt to the parameter vector $(\alpha, \beta, \sigma, \mu)'$

2. Stable distributions have pareto-like heavy tails

$$x^\alpha P(|Z_1| > x) \rightarrow \sigma^\alpha c(\alpha) \quad \text{and} \quad c(\alpha) = \left(\int_0^\infty t^{-\alpha} \sin(t) dt \right)^{-1}.$$

3. Location/scale family

$$f(z; (\alpha, \beta, \sigma, \mu)) = \sigma^{-1} f(\sigma^{-1}(z - \mu); (\alpha, \beta, 1, 0))$$

4. Unimodal. $f(\bullet; (\alpha, \beta, 1, 0))$ is unimodal

3. Maximum Likelihood Estimation

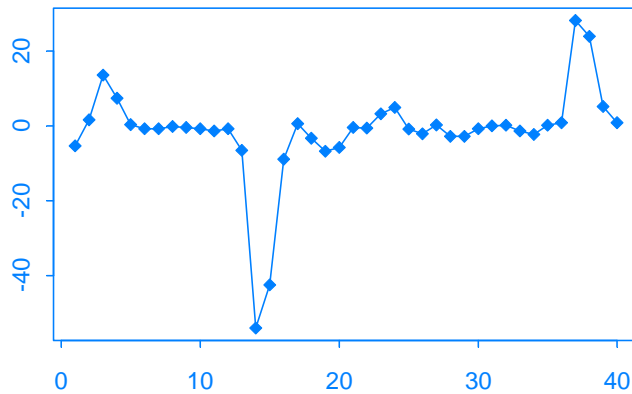
Estimation for nonCausal and/or All-Pass Models

- 👉 Second-order moment techniques do not work (work for causal AR!)
 - least squares
 - Gaussian likelihood
- 👉 Higher-order cumulant methods
 - Giannakis and Swami (1990)
 - Chi and Kung (1995)
- 👉 Non-Gaussian likelihood methods
 - likelihood approximation assuming known density
 - quasi-likelihood
- 👉 Other
 - LAD- least absolute deviation
 - Rank-based estimation (minimum dispersion)

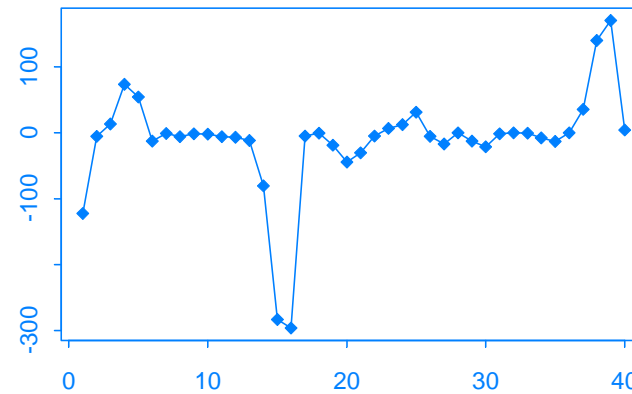
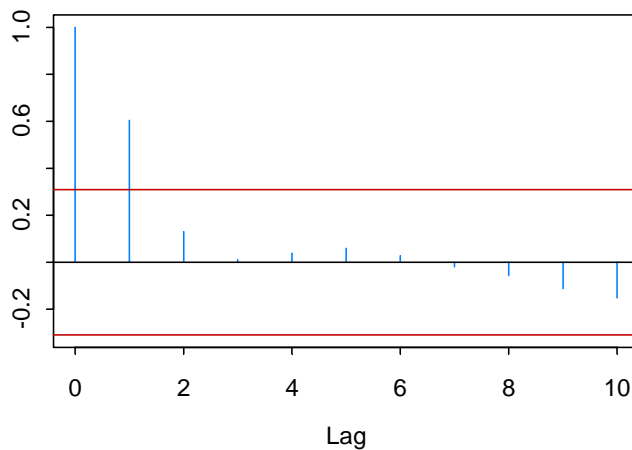
Realizations of an invertible and noninvertible MA(2) processes

Model: $X_t = \theta_*(B) Z_t$, $\{Z_t\} \sim \text{IID}(\alpha = 1)$, where

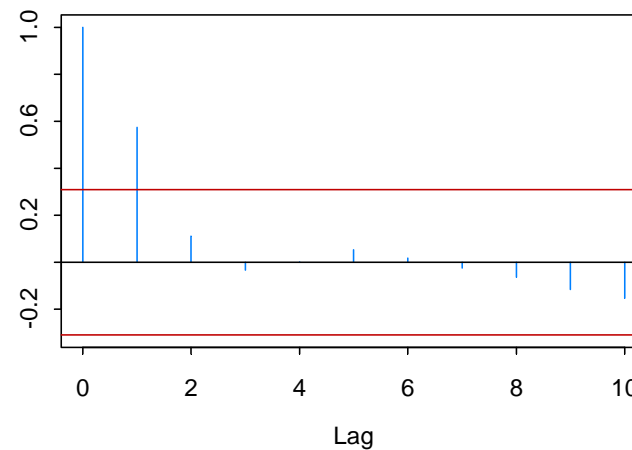
$\theta_i(B) = (1 + 1/2B)(1 + 1/3B)$ and $\theta_{ni}(B) = (1 + 2B)(1 + 3B)$



ACF



ACF



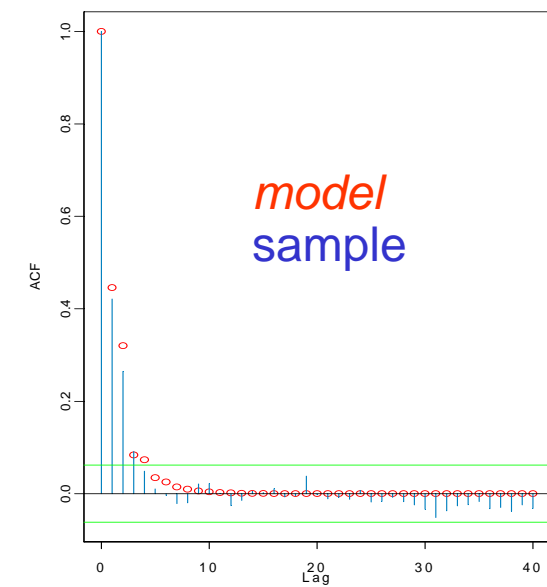
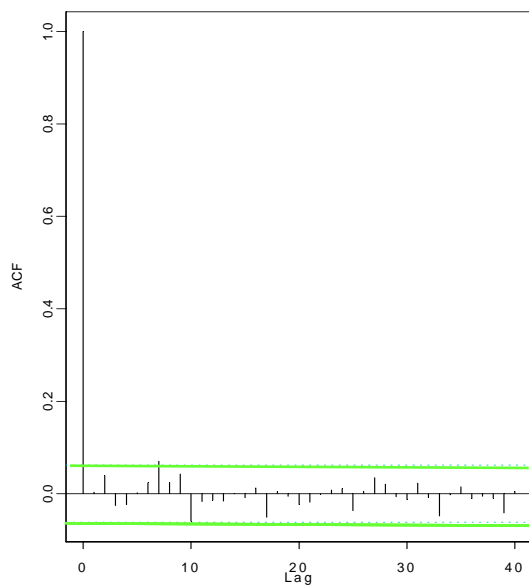
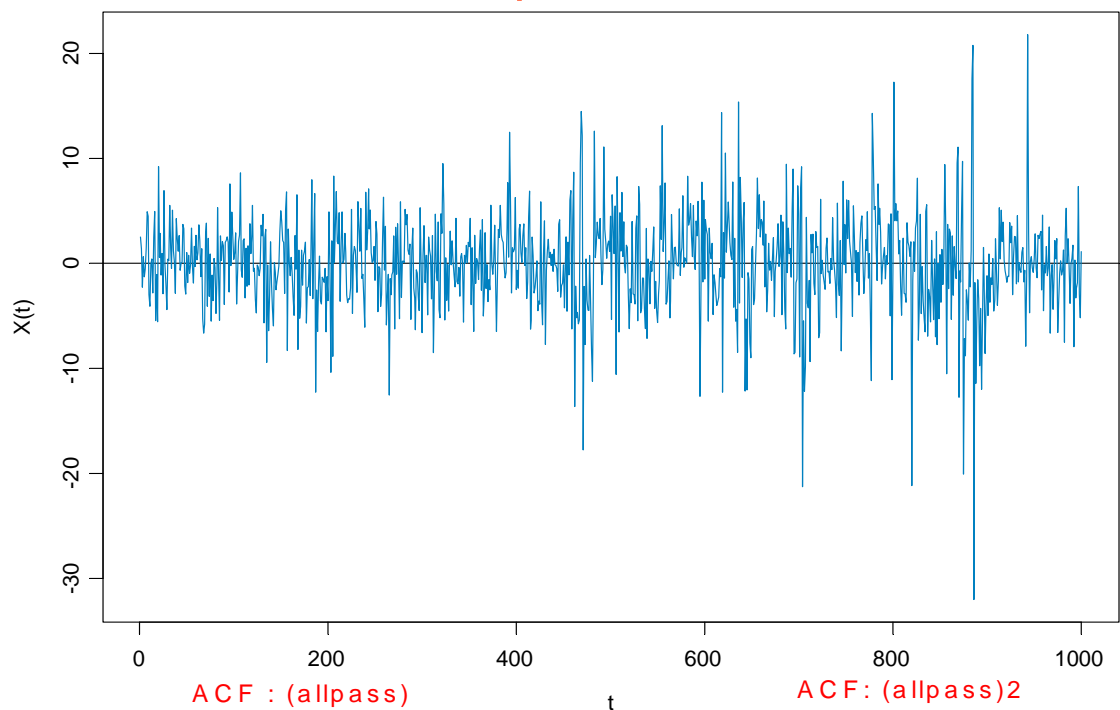
3. Estimation for AR Models

Estimation strategies for *causal* AR models:

- LS estimation (Davis and Resnick `86)
- Maximum Gaussian likelihood (Mikosch, Gadrich, Kluppelberg, Adler `95)
- LAD- least absolute deviation (special case of M-Estimation) (Davis, Knight, Liu `92; Davis `96)

4. Allpass models

Realization
from an all-
pass model
of order 2
(t3 noise)



3. MLE—allpass models: approximating the likelihood

Data: (X_1, \dots, X_n)

Model:
$$X_t = \phi_{01}X_{t-1} + \dots + \phi_{0p}X_{t-p} - (Z_{t-p} - \phi_{01}Z_{t-p+1} - \dots - \phi_{0p}Z_t) / \phi_{0r}$$

where ϕ_{0r} is the last non-zero coefficient among the ϕ_{0j} 's.

Noise: $z_{t-p} = \phi_{01}z_{t-p+1} + \dots + \phi_{0p}z_t - (X_t - \phi_{01}X_{t-1} - \dots - \phi_{0p}X_{t-p}),$

where $z_t = Z_t / \phi_{0r}$.

More generally define,

$$z_{t-p}(\phi) = \begin{cases} 0, & \text{if } t = n+p, \dots, n+1, \\ \phi_{01}z_{t-p+1}(\phi) + \dots + \phi_{0p}z_t(\phi) - \phi(B)X_t, & \text{if } t = n, \dots, p+1. \end{cases}$$

Note: $z_t(\phi_0)$ is a close approximation to z_t (initialization error)

Assume that Z_t has stable pdf f_τ and consider the vector

$$\mathbf{z} = (\underbrace{X_{1-p}, \dots, X_0, z_{1-p}(\phi), \dots, z_0(\phi)}_{\text{independent pieces}}, \underbrace{z_1(\phi), \dots, z_{n-p+1}(\phi), \dots, z_n(\phi)}_{\text{independent pieces}})'$$



independent pieces

Joint density of \mathbf{z} :

$$h(\mathbf{z}) = h_1(X_{1-p}, \dots, X_0, z_{1-p}(\phi), \dots, z_0(\phi)) \cdot \left(\prod_{t=1}^{n-p} f_\tau(\phi_q z_t(\phi)) |\phi_q| \right) h_2(z_{n-p+1}(\phi), \dots, z_n(\phi)),$$

and hence the joint density of the data can be approximated by

$$h(\mathbf{x}) = \left(\prod_{t=1}^{n-p} f_\tau(\phi_q z_t(\phi)) |\phi_q| \right)$$

where $q = \max\{0 \leq j \leq p: \phi_j \neq 0\}$.

Log-likelihood: Let $\tau = (\alpha, \text{sgn}(\phi_q)\beta, \sigma / |\phi_q|, \mu / \phi_q)'$

$$\begin{aligned} L(\phi, \tau) &= \sum_{t=1}^{n-p} (\ln f(\phi_q z_t(\phi); (\alpha, \beta, \sigma, \mu)) + \ln |\phi_q|) \\ &= \sum_{t=1}^{n-p} \ln \left[\frac{|\phi_q|}{\sigma} f \left(\frac{z_t(\phi) - \mu / \phi_q}{\sigma / \phi_q}; (\alpha, \beta, 1, 0) \right) \right] \\ &= \sum_{t=1}^{n-p} \ln [f(z_t(\phi); (\alpha, \text{sgn}(\phi_q)\beta, \sigma / |\phi_q|, \mu / \phi_q))] \\ &= \sum_{t=1}^{n-p} \ln [f(z_t(\phi); \tau)] \end{aligned}$$

3. MLE—noncausal AR models

One can go through a similar calculation for noncausal AR models.

Model:

$$X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + Z_t$$

$$Z_t = (1 - \phi_1 B + \dots + \phi_p B^p) X_t \quad \text{B=backward shift operator}$$

$$Z_t = (1 - \theta_1 B + \dots + \theta_r B^r) (1 - \theta_{r+1} B + \dots + \theta_{r+s} B^s) X_t$$

$$Z_t = \theta^+(B)\theta^*(B) X_t$$

where $\theta^+(z)$ is the good (**causal**) AR polynomial and $\theta^*(B)$ is the bad (**purely noncausal**) AR polynomial.

Likelihood: $\tau = (\alpha, \text{sgn}(\phi_q)\beta, \sigma / |\phi_q|, \mu / \phi_q)'$

$$L(\theta, \tau) = \sum_{t=p+1}^n \left(\ln[f(Z_t(\theta); \tau)] + \ln |\theta_p| I(s > 0) \right)$$

Reparameterize: Denote the true parameters by ϕ_0 and τ_0 and set

$$u = n^{1/\alpha_0} (\phi - \phi_0) \quad \text{and} \quad v = n^{1/2} (\tau - \tau_0)$$

which are elements of \mathbb{R}^p and \mathbb{R}^4 , respectively. Now the log-likelihood can be re-expressed as a continuous function on $\mathbb{R}^p \times \mathbb{R}^4$ given by

$$\begin{aligned} W_n(u, v) &= L(\phi_0 + n^{-1/\alpha_0} u, \tau_0 + n^{-1/2} v) - L(\phi_0, \tau_0) \\ &= \sum_{t=1}^{n-p} \ln[f(z_t(\phi_0 + n^{-1/\alpha_0} u); \tau_0 + n^{-1/2} v)] - \sum_{t=1}^{n-p} \ln[f(z_t(\phi_0); \tau_0)] \end{aligned}$$

Note:

$$(\hat{u}_n, \hat{v}_n) = \arg \max_{u, v} W_n(u, v) = \left(n^{1/\alpha_0} (\hat{\phi} - \phi_0), n^{1/2} (\hat{\tau} - \tau_0) \right)$$

Result: $W_n(u, v) \rightarrow_d W(u) + v' \mathbf{N} - 2^{-1} v' \mathbf{I}(\tau_0) v$ on $C(\mathbb{R}^p \times \mathbb{R}^4)$, where

- $\mathbf{I}(\tau_0) := -\left[\mathbb{E} \left\{ \partial^2 \ln f(z; \tau) / (\partial \tau_i \partial \tau_j) \right\} \right]_{i,j=1}^4$ is the Fisher information for a stable density.
- $\mathbf{N} \sim \mathbf{N}(\mathbf{0}, \mathbf{I}(\tau_0))$ is a normal random vector independent of W .
- W is the process

$$W(u) = \sum_{k=1}^{\infty} \sum_{j \neq 0} \left\{ \ln f \left(z_{k,j} + [\tilde{c}(\alpha_0)]^{1/\alpha_0} \sigma_0 |\phi_{0r}|^{-1} c_j(u) \delta_k \Gamma_k^{-1/\alpha_0}; \tau_0 \right) - \ln f \left(z_{k,j}; \tau_0 \right) \right\}$$

- $c_j(u)$ are found through the Laurent series identity

$$\sum_{j \neq 0} c_j(u) z^j = u' \left[- (z^{-k} / \phi_0(z)) + (z^k / \phi_0(z^{-1})) \right]_{k=1}^p$$

- $\{z_{k,j}\}$ is iid $z_{1,1} =_d Z_1 / \phi_{0r}$
- $\{\delta_k\}$ is iid $P(\delta_k=1) = p = 1 - P(\delta_k=-1)$.
- $\Gamma_k = E_1 + \dots + E_k$, where $\{E_k\}$ is iid unit exponentials
- $\{z_{k,j}\}$, $\{\delta_k\}$, and $\{E_k\}$ are mutually independent

Deconstructing the limit result and limit process:

The limit process in the following

$$W_n(u, v) \rightarrow_d W(u) + v' \mathbf{N} - 2^{-1} v' \mathbf{I}(\tau_0) v$$

consists of two independent pieces:

1. $W(u)$ which governs the limit behavior of the AR or AP model parameters ϕ_1, \dots, ϕ_p . Set $\xi = \arg \max_u W(u)$
2. $v' \mathbf{N} - 2^{-1} v' \mathbf{I}(\tau_0) v$ which governs the limit behavior of the stable parameters $(\alpha, \beta, \sigma, \mu)$. Set $\eta = \arg \max_v v' \mathbf{N} - 2^{-1} v' \mathbf{I}(\tau_0) v$, is equal to $\eta = \mathbf{I}^{-1}(\tau_0) \mathbf{N} \sim N(0, \mathbf{I}^{-1}(\tau_0))$.

Theorem: There exists a sequence of maximizers of the likelihood function such that

$$n^{1/\alpha_0} (\hat{\phi}_{ML} - \phi_0) \rightarrow_d \xi \quad \text{and} \quad n^{1/2} (\hat{\tau}_{ML} - \tau_0) \rightarrow_d \eta.$$

3. MLE—allpass models

$$n^{1/\alpha_0} (\hat{\phi}_{ML} - \phi_0) \rightarrow_d \xi, \quad n^{1/2} (\hat{\tau}_{ML} - \tau_0) \rightarrow_d \eta \sim \mathbf{N}(\mathbf{0}, \mathbf{I}^{-1}(\tau_0)).$$

Remarks:

- The distribution of ξ is generally intractable. However, one can use bootstrapping techniques (see later example and Davis and Wu '97).
- The scaling for the AR parameters is $n^{1/\alpha}$, which is much faster than the standard $n^{1/2}$ rate.
- The limit behavior of the estimates of the stable parameters is the same as for an iid sequence (see DuMouchel '73).

4. Simulation Results

Simulation setup:

- 300 replicates of a non-causal AR(2) model

$$X_t = -1.2 X_{t-1} + 1.6 X_{t-2} + Z_t \quad (\text{zeros of AR polyn } 1.25, -.5)$$

- noise distribution is stable with two sets of parameter values:

- $\alpha = .8 \quad \beta = .5 \quad \sigma = 1.0 \quad \mu = 0.0$ (really heavy!)

- $\alpha = 1.5 \quad \beta = .5 \quad \sigma = 1.0 \quad \mu = 0.0$

- sample sizes $n=500$
- estimation is maximum likelihood

4. Simulation Results

	Asymp SD	Empirical			Asymp SD	Empirical	
		Mean	Std Dev			Mean	Std Dev
$\phi_1 = -1.2$		-1.200	0.004	$\phi_1 = -1.2$		-1.200	0.004
$\phi_2 = 1.6$		1.600	0.004	$\phi_2 = 1.6$		1.600	0.004
$\alpha = 0.8$	0.051	0.798	0.041	$\alpha = 0.8$	0.049	0.800	0.039
$\beta = 0.0$	0.067	-0.001	0.068	$\beta = 0.5$	0.058	0.502	0.056
$\sigma = 1.0$	0.077	0.997	0.073	$\sigma = 1.0$	0.074	0.997	0.071
$\mu = 0.0$	0.054	-0.002	0.057	$\mu = 0.0$	0.062	-0.004	0.064
$\phi_1 = -1.2$		-1.212	0.083	$\phi_1 = -1.2$		-1.204	0.078
$\phi_2 = 1.6$		1.605	0.065	$\phi_2 = 1.6$		1.598	0.062
$\alpha = 1.5$	0.071	1.502	0.069	$\alpha = 1.5$	0.070	1.499	0.071
$\beta = 0.0$	0.137	0.010	0.128	$\beta = 0.5$	0.121	0.509	0.128
$\sigma = 1.0$	0.048	0.999	0.066	$\sigma = 1.0$	0.047	0.997	0.056
$\mu = 0.0$	0.078	-0.006	0.078	$\mu = 0.0$	0.078	0.000	0.083

5. Walmart revisited---residuals from noncausal model

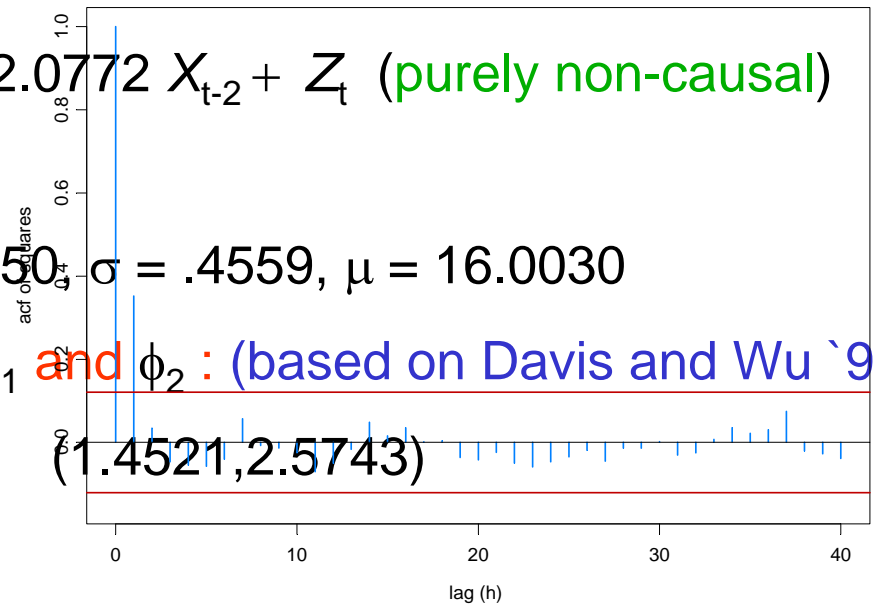
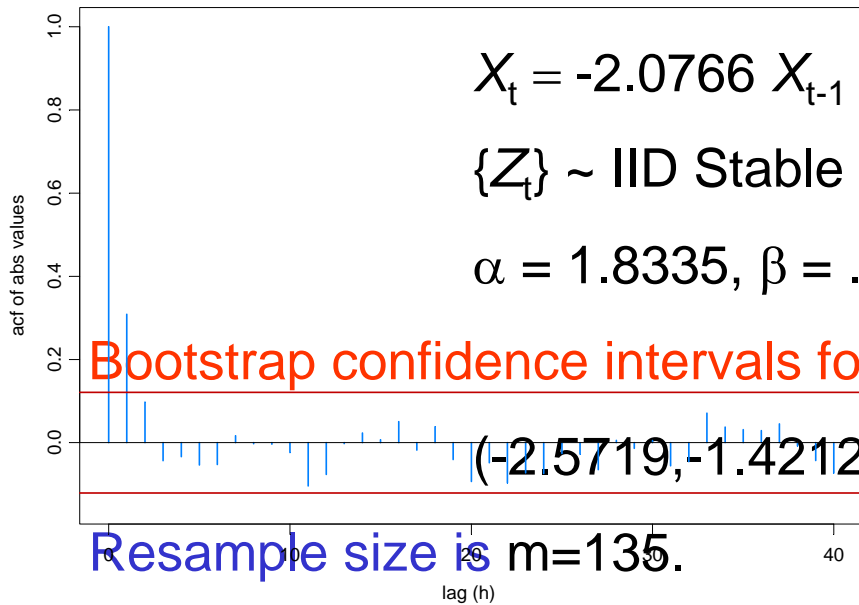
Analysis of the ACF and PACF of the time series (n=274) suggests that $\{X_t\}$ follows an AR (1) or AR(2).

A *causal* AR(2) fit (using Gaussian MLE) is

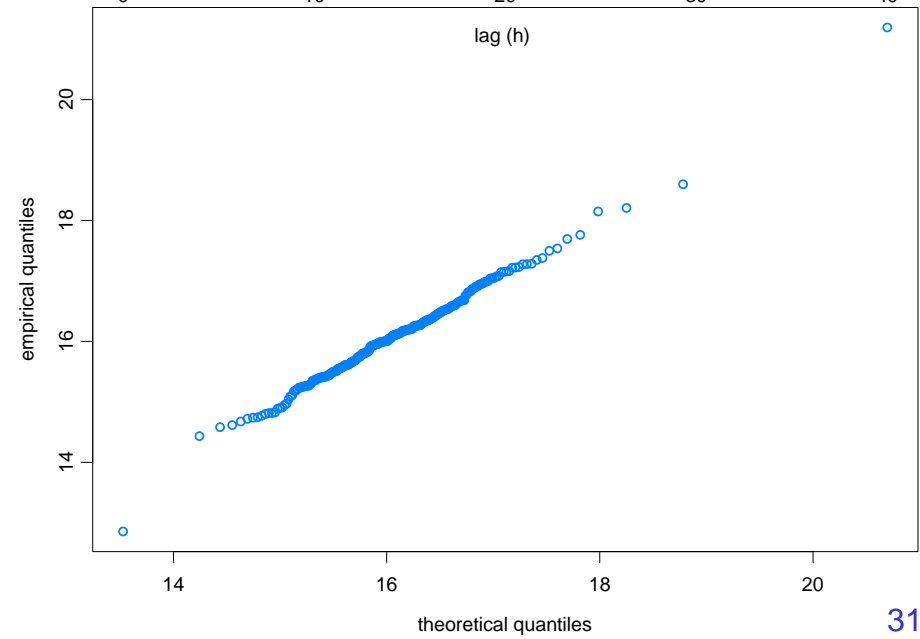
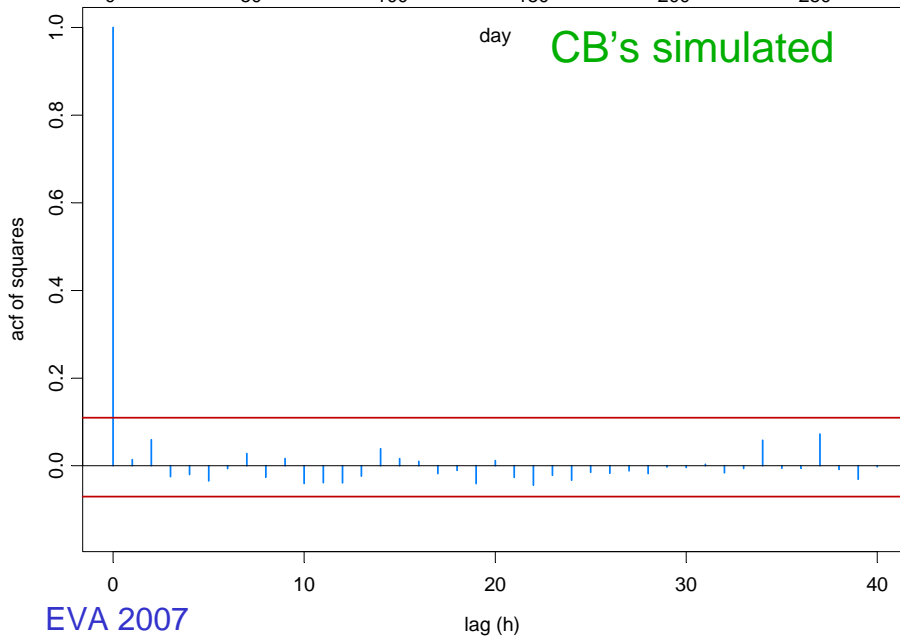
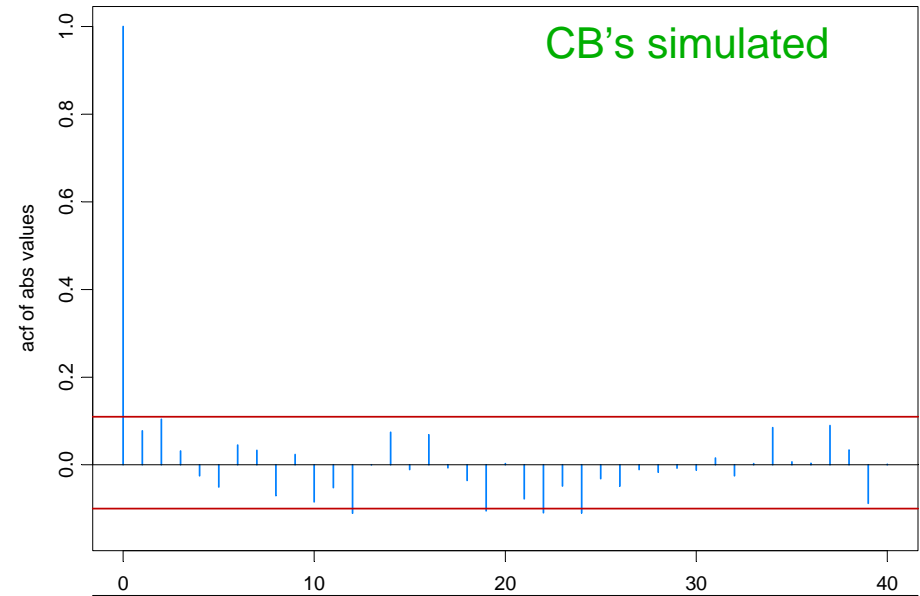
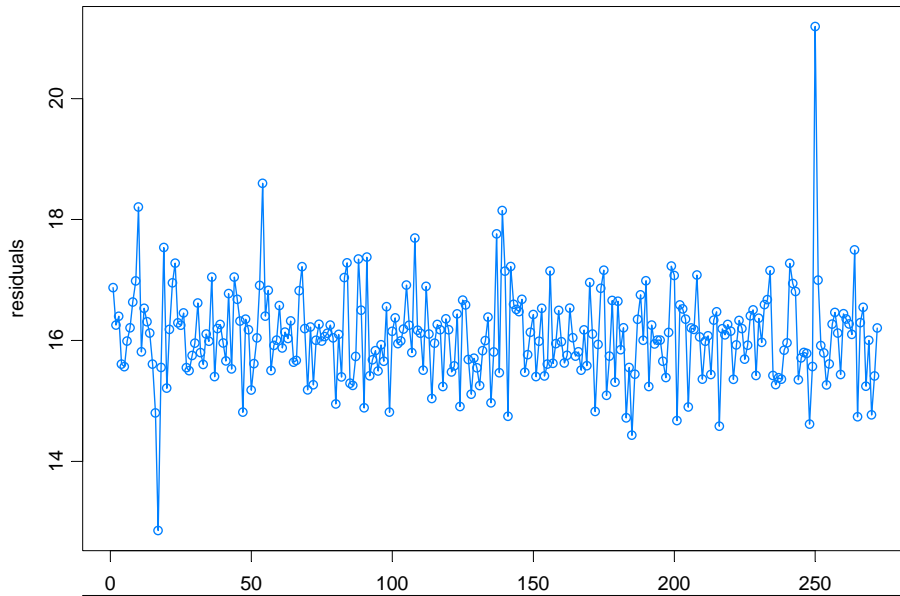
$$X_t = .4455 X_{t-1} + .1025 X_{t-2} + Z_t$$

The estimated residuals were uncorrelated but ***dependent***.

Maximum-likelihood model:



5. Walmart—analysis of residuals from noncausal model



6th Conference on Extremes: Fort Collins, Colorado

June 22-26, 2009



Graybill VIII Conference in 2009

6th Conference on Extremes

Fort Collins, Colorado

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